## Math 466 Exercises for Week 4

## March 13, 2025

1. Following the steps below prove the following:

Let  $U \subseteq \mathbb{R}^n$  and suppose  $f: U \to \mathbb{R}^n$  is distance preserving. Then there exists an isometry  $\hat{f}: \mathbb{R}^n \to \mathbb{R}^n$  such that  $\hat{f}|_U = f$ .

- (a) If  $u \in U$ , then  $g = T_{-f(u)} \cdot f \cdot T_u : T_{-u}(U) \to \mathbb{R}^n$  is distance preserving and fixes the origin. Thus WLOG we may assume U contains the origin and f fixes the origin.
- (b) Show that  $f(x) \cdot f(y) = x \cdot y$  for all  $x, y \in U$ .
- (c) Let  $V = \langle U \rangle$  be the subspace spanned by U. Given  $v \in V$ , write  $v = \sum_{i=1}^{n} c_i u_i$  for some  $u_i \in U$  and define  $\hat{f} : V \to \mathbb{R}^n$  by  $\hat{f}(v) = \sum_{i=1}^{n} c_i f(u_i)$ . Show that  $\hat{f}$  is well defined, distance preserving linear transformation.
- (d) Let  $W = \langle f(U) \rangle$  and note that V and W have the same dimension. Find a linear isometry  $\overline{f} : \mathbb{R}^n \to \mathbb{R}^n$  which extends  $\widehat{f}$ . (Hint: Use orthogonal complements.)
- 2. Recall that, given an isometry  $f \in Isom(\mathbb{R}^2)$ , we write  $f = T_{\vec{v}} \cdot A$  where  $T_{\vec{v}}$  is a translation and  $A \in O(2)$ is an orthogonal matrix. Then, if is O.P. if det(A) = 1 an O.R. otherwise.  $Isom^+(\mathbb{R}^2)$  is the subgroup of  $Isom(\mathbb{R}^2)$  consisting of orientation preserving isometries. L Show that  $Isom^+(\mathbb{R}^2) \cong \mathbb{R}^2 \rtimes SO(2)$ .
- 3. Show that the square of an O.R. isometry of  $\mathbb{R}^n$  is a translation.

For the remaining exercises, all elements belong to  $Isom(\mathbb{R}^2)$ .

- 4. Show that any glide reflecton can be written as the product of a reflection and a rotation. Is this decomposition unique?
- 5. Let f and g be glide reflections about the lines  $\ell_1$  and  $\ell_2$  respectively. Show that  $f \cdot g$  is a translation if and only if  $\ell_1 \parallel \ell_2$ .
- 6. Prove that any two reflections are conjugate.
- 7. Let f, g be rotations by  $\theta_1$  and  $\theta_2$  where  $\theta_i \in (0, 2\pi)$ . Show that f and g are conjugate if and only if  $\theta_1 = \theta_2$ .
- 8. Let  $T_{\vec{v}}$  and  $T_{\vec{w}}$  be two translations. Show that they are conjugate if and only if  $||\vec{v}|| = ||\vec{w}||$ .